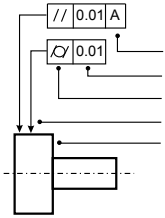
JENOPTIK

Form measuring systems from Jenoptik
Geometrical tolerancing in practice

DAkkS

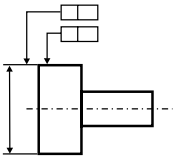
Tolerance frame



Toleranced elements

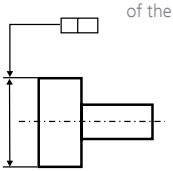
Indicating arrow to contour line or subsidiary line (offset from dimension line):

if the tolerance refers to the line or area.



Indicating arrow as an extension of the dimension line:

if the tolerance applies for the axis or median plane or a point of the element.

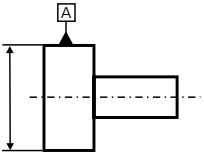


Datums

Datum triangle with datum letters

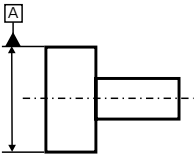
on the contour line of the element or on the subsidiary line:

if the displayed datum is a line or area.

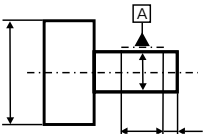


as an extension of the dimension line:

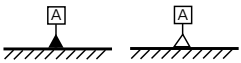
if the datum is the axis, the median plane or an appropriately dimensioned point.



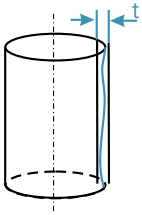
Restriction of the datum to an area of the element as a dot-dash line with dimensioning.



A filled in or empty datum triangle has the same meaning.

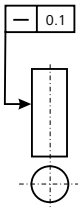


Straightness



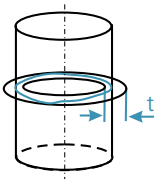
The tolerance zone is limited by two parallel lines at a distance *t* apart. Every envelope line of the toleranced cylinder must be between these two parallel lines.

Example



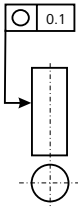
Every envelope line of the toleranced cylinder surface must be between two parallel lines at a distance apart of 0.1.

Roundness



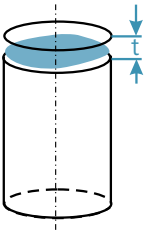
The tolerance zone is limited by two concentric circles at a distance *t* apart. The circumference line of the toleranced cylinder must be within a circle ring of the zone width *t*, in every radial section plane.

Example



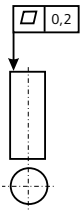
The circumference line of the toler-anced cylinder must be within a circle ring of the zone width 0.1 in every radial section plane.

Flatness



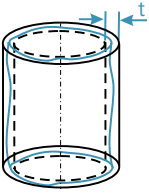
The tolerance zone is limited by two parallel planes at a distance *t* apart, the dimensions of which correspond to those of the toleranced area. The real workpiece area must be between the two parallel planes at distance *t* apart.

Example



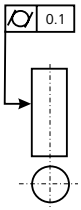
The real workpiece area must be between two parallel planes at a distance apart of 0.2.

Cylindricity



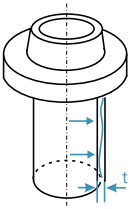
The tolerance zone for the cylinder envelope area limits the deviation of the roundness, the straightness of the envelope line and the parallelism of the envelope line to the cylinder axis. It is formed by two coaxial cylinders with the radial distance *t*.

Example



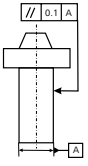
The toleranced cylindrical area must be between two coaxial cylinders with a radial distance of 0.1.

// Parallelism



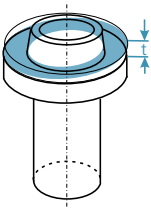
The tolerance zone within which the envelope lines of the toleranced cylinder must lie is limited by two parallel lines at a distance *t* apart which run parallel to the datum plane.

Example



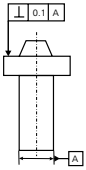
Every single envelope line of the toleranced area must be between two parallel lines that are at a distance of 0.1 apart, and are parallel to the center axis.

⊥ Perpendicularity



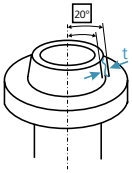
The tolerance zone is limited by two parallel planes at a distance *t* apart, which are perpendicular to the datum axis. The toleranced plane face must be between these two planes.

Example



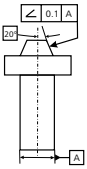
All points/circle lines of the toleranced area must be between two parallel planes that are at a distance of 0.1 apart, and are perpendicular to the datum plane.

∠ Angularity



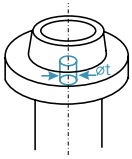
The tolerance zone is limited by two parallel planes at a distance *t* apart at the nominal angle to the datum axis.

Example



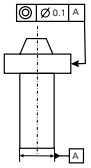
All points of the toleranced area must be between two parallel planes that are at a distance apart of 0.1, and are angled at 20° to the datum axis.

◎ Coaxiality



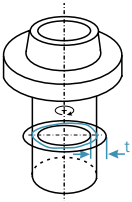
The tolerance zone is limited by a cylinder of diameter *t*, the axis of which matches the datum axis.
The actual axis of the toleranced element must be within the tolerance zone.

Example



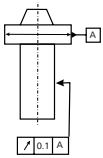
The axis of the toleranced cylinder must be within a cylinder that has a diameter of 0.1 and is coaxial to the datum axis A.

Radial run-out



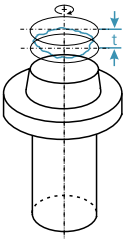
In every radial section plane perpendicular to the surface, the tolerance zone is limited by two concentric circles at a distance *t* apart, the common center point of which is on the datum axis. The radial run-out tolerance applies generally for a full revolution of the toleranced element around the datum axis.

Example



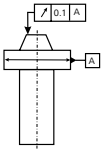
The circumference line of every radial section plane of the toleranced cylindrical area must be between two concentric circles at a distance apart of 0.1 with their common center point on the datum axis A.

Axial run-out



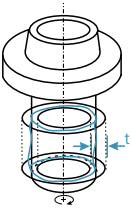
The tolerance zone is limited in every radial distance of two circles at a distance *t* apart. The circles are in a cylinder, the axis of which matches the datum axis. The diameter of the cylinder can adopt any value of the diameter of the plane face.

Example



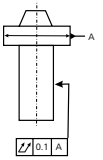
Every circle line of the toleranced area must be between two parallel circle planes at a distance apart of 0.1 with their common center point on the datum axis A.

Total radial run-out



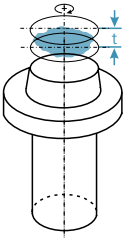
The tolerance zone is limited by two coaxial cylinders at a distance *t* apart, the axes of which match the datum axis. After several rotations around the datum axis and axial shift of the transducer all points of the toleranced element must be within the tolerance zone.

Example



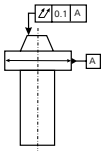
The toleranced cylindrical area must be between two coaxial cylinders with a radial distance apart of 0.1 with their common axis on the datum axis A.

Total axial run-out



The tolerance zone is limited by two parallel planes at a distance *t* apart, which are perpendicular to the datum (rotational) axis. After several rotations around the datum axis and radial shift of the transducer, all points of the surface of the tolerance plane face must be within the tolerance zone.

Example



The toleranced area must be between two parallel circle planes at a distance apart of 0.1 with their common center point on the datum axis A.

obal presence.

Our service range

Metrology
Tactile metrology
Pneumatic metrology
Optical metrology

Product range
Roughness measurement
Contour measurement
Form measurement
Optical shaft measurement
Dimensional measurement
Optical surface inspection

Inspection process
In-process
Post-process
PLC
Final inspection
Measuring room

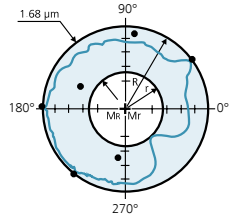
Service
System solutions
DAkkS-DKD calibration service
Consulting, training and service

JENOPTIK

www.jenoptik.com/metrology

Evaluation method

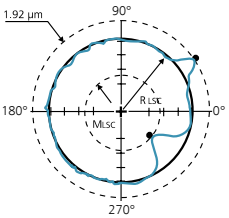
Effect and function of different evaluation methods on the roundness evaluation



MZCI
Minimum Zone Circle

Concentric inner and outer perimeter circles with a minimum radial distance, and which enclose the roundness profile.

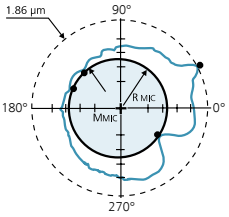
Individual profile peaks influence the center point **considerably**.
Gives the least possible form error.



LSCI
Least Square Circle

Circle through the roundness profile with minimum sum of profile deviation squares.

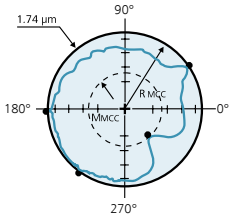
Individual profile peaks influence the center point **only a little**.
Very suitable for stable datum formation.



MICI
Maximum Inscribed Circle

Maximum circle inscribed in the roundness profile for inside areas.

The method is used for form measurement of the inside diameter.



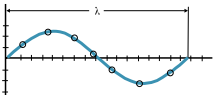
MCCI
Minimum Circumscribed Circle

Minimum circle circumscribing the roundness profile for outside areas.

The method is used for form measurement of the outside diameter.

Filtering method

Definition according to ISO 11562 or ISO 16610-21 for roughness and form measurement.

Filter characteristic:	Gaussian amplitude transmission function
Amplitude damping at cut-off λc:	50 %
Number of points per wave	 At least 7 points per wave must be selected.
Roundness measurement:	Specification of cut-off in w/r (waves/revolution). The specification is independent of the workpiece diameter.
Recommended cut-off numbers:	15, 50, 150, 500 w/r
Conversion of w/r to wavelength:	λc = D x 3.14/number of cut-offs
Straightness measurement:	Specification of cut-off in mm
Recommended cut-offs:	0.25; 0.8; 2.5; 8.0 mm

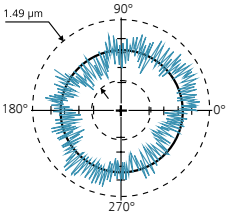
Standards of practical relevance

For measurement of roundness, straightness and flatness

ISO 1101	Geometrical Product Specifications (GPS) – Geometrical tolerancing – Tolerances of form, orientation, location and run-out
ISO 12180-1	Geometrical Product Specifications (GPS), Cylindricity – Part 1 Vocabulary and parameters of cylindricity
ISO 12181-1	Geometrical Product Specifications (GPS), Roundness –Part 1 Vocabulary and parameters of roundness
ISO 12780-1	Geometrical Product Specifications (GPS), Straightness – Part 1 Vocabulary and parameters of straightness
ISO 12781-1	Geometrical Product Specifications (GPS), Flatness – Part 1 Vocabulary and parameters of flatness
VDI/VDE 2631 Sheet 1	Form measurement – Basic principals of the determination of form and positional deviations
VDI/VDE 2631 Sheet 2	Form measurement – Determination of the sensitivity of the signal transmittal chain
VDI/VDE 2631 Sheet 3	Form measurement – Filter characteristics and selection

Filter stages

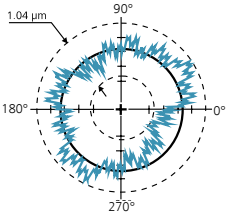
Filter effect of different cut-off numbers on the roundness result.
Gauss filter 50 %



No filter

1.49 µm

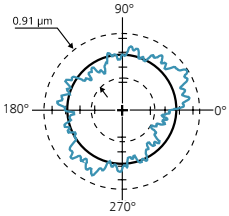
RONt (MZCI) = 1.49 µm



Filter 150 W/R

1.04 µm

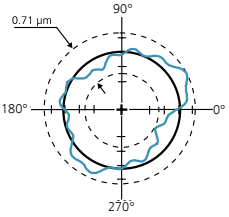
RONt (MZCI) = 1.04 µm



Filter 50 W/R

0.91 µm

RONt (MZCI) = 0.91 µm



Filter 15 W/R

0.71 µm

RONt (MZCI) = 0.71 µm

Tolerances of form, orientation, location and run-out according to ISO 1101

Using the standardized tolerance specifications, tolerance zones are determined within which the toleranced elements (line, area, point, axis, median plane) of the workpiece must lie.

Form tolerance refers to the tolerance zone that limits the deviation of a form element from its ideal geometry (straightness, flatness, roundness, cylindricity) and is orientated exclusively to the toleranced element. Only the tolerances for profile any line and profile any surface require theoretically exact dimension specifications and datums.

A orientation tolerance refers to a tolerance zone with which the deviation from the general direction (parallelism, perpendicularity, angularity) between the toleranced element and the datum and form deviation of the toleranced element is limited.

Location tolerance refers to the tolerance zone which limits the deviation of the toleranced element (position, coaxiality, concentricity, symmetry) from its ideal geometrical location, which must be defined clearly by a datum or a system of datums.

A run-out tolerance refers to a tolerance zone which limits the form and position deviations of envelope areas or plane faces in relation to the rotational axis.

General tolerances according to ISO 2768 part 2

For workpieces produced by cutting — All dimensions in mm

Tolerance class H

Nominal dimension range	...10	> 10 ...30	> 30 ...100	> 100 ...300	> 300 ...1000	> 1000 ...3000
⏤ ▱	0.02	0.05	0.1	0.2	0.3	0.4
⊥		0.2		0.3	0.4	0.5
⌯				0.5		
↗				0.1		

Tolerance class K

Nominal dimension range	...10	> 10 ...30	> 30 ...100	> 100 ...300	> 300 ...1000	> 1000 ...3000
⏤ ▱	0.05	0.1	0.2	0.4	0.6	0.8
⊥		0.4		0.6	0.8	1.0
⌯			0.6		0.8	1.0
↗				0.2		

Tolerance class L

Nominal dimension range	...10	> 10 ...30	> 30 ...100	> 100 ...300	> 300 ...1000	> 1000 ...3000
⏤ ▱	0.1	0.2	0.4	0.8	1.2	1.6
⊥		0.6		1.0	1.5	2.0
⌯		0.6		1.0	1.5	2.0
↗				0.5		

◯ Tolerance value corresponds to the diameter tolerance or maximum general tolerance for the radial run-out.

// Tolerance value corresponds to the maximum value in comparison of the dimension tolerance of the distance dimension with the general tolerance for the straightness or the flatness of the form elements being inspected.